



GREY-BOX MODELLING OF AN INDUSTRIAL HYDRODESULPHURIZATION PROCESS



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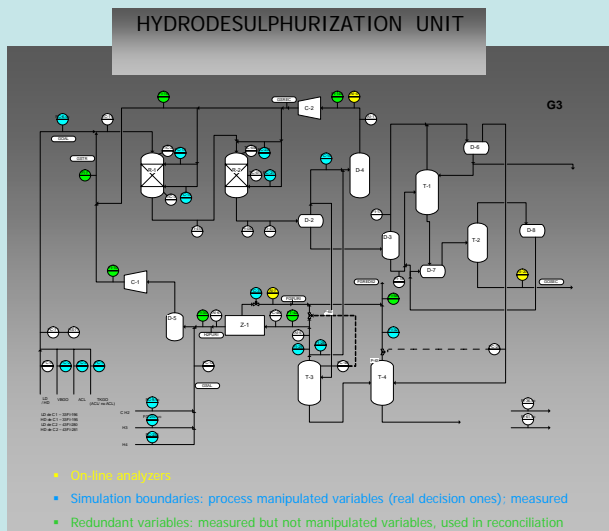
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Abstract

A reduced order model of a hydrodesulphurization plant which aims to provide dynamic hydrogen consumption rates as a function of the plant hydrocarbon load is being developed. This is part of a wider project oriented to the optimal management of the hydrogen network of a refinery, where hydrogen production should be dynamically adjusted to consumption as much as possible so as to reduce excess losses. The proposed model combines physico-chemical principles with black box elements.



METHODOLOGY FOR OFF-LINE PARAMETER ESTIMATION

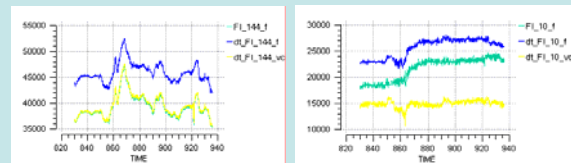
1. - DATA RECONCILIATION

In order to take advantage of all the available measures

$$\min \sum_j (flow_j - flow_j^{vc})^2$$

Extended to all the measured flowrates (green arrow)
Model variable that fits balance perfectly (blue arrow)
Experimental value corrected by means of molecular weight obtained from model (purple arrow)

Boundaries (inputs): $flow_j = flow_j^{vc} + bias$ Decision variable for the optimization problem to solve reconciliation



2. - CALCULATION OF PARAMETERS – Inverse model

- Experimental data of available measures corresponding to model output variables are used to identify the kinetic parameters of the model
 - H₂ purity of the recycle stream from the high pressure flash drum
 - Outlet flow to fuel gas from low pressure separations
 - Sulfur concentration of the desulfurized hydrocarbon stream

3. - NEURAL NETWORK ARCHITECTURE

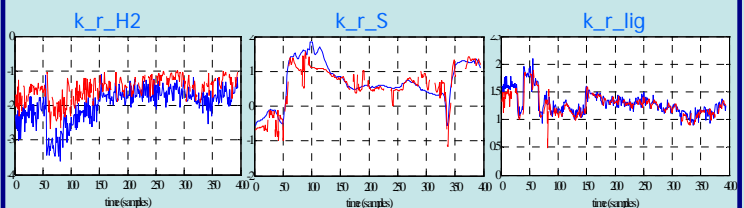
- Experimental data of external inputs are used as regressors for kinetic parameters estimation
 - H₂ concentration in the reactor
 - Inlet temperature to the reactor
 - Flowrate fractions of different hydrocarbon mixed in feed

NARX model
1st order in model outputs
2nd order in external inputs

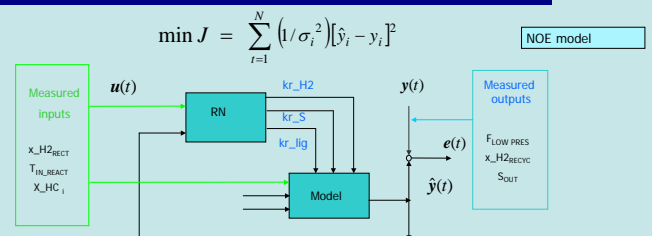
3 NN
5 hidden hyperbolic nodes
1 output linear node

Trained with the Levenberg-Marquardt method.

4. - NEURAL NETWORK VALIDATION



5. - FUTURE WORK – Implementation of NN in simulation



REDUCED DYNAMIC MODEL

COMPONENTS
H₂, CH₄, S, HC (hydrocarbon)

Reactor - dynamic model

$$0 = WM_{IN_R} - WM_{OUT_R} \quad M_L | = \text{kmol}, x | = \% \text{ mol}, WM | = \text{kg/h}, W | = \text{kmol/h}$$

$$M_L \cdot x_{H_2}^R = W_{IN_R} \cdot x_{H_2}^{IN_R} - W_{OUT_R} \cdot x_{H_2}^R - ce_{H_2_S} \cdot k_{r_S} \cdot x_{H_2}^R \cdot x_S^R \cdot M_L - k_{r_H_2} \cdot x_{H_2}^R \cdot M_L$$

$$M_L \cdot x_S^R = W_{IN_R} \cdot x_S^{IN_R} - W_{OUT_R} \cdot x_S^R - k_{r_S} \cdot x_{H_2}^R \cdot x_S^R \cdot M_L$$

$$M_L \cdot x_{CH_4}^R = W_{IN_R} \cdot x_{CH_4}^{IN_R} - W_{OUT_R} \cdot x_{CH_4}^R + k_{r_{lig}} \cdot x_{H_2}^R \cdot M_L$$

Flash drum - static model

$$F = V + L$$

$$F \cdot x_{CH_4}^F = V \cdot x_{CH_4}^V + L \cdot x_{CH_4}^L$$

$$F \cdot x_{HC}^F = L \cdot x_{HC}^L$$

$$F \cdot x_S^F = L \cdot x_S^L$$

$$1 = x_{H_2}^L + x_{CH_4}^L + x_S^L + x_{HC}^L$$

$$1 = x_{H_2}^V + x_{CH_4}^V$$

$$x_{H_2}^V = pv_{H_2} \cdot (P^o_{H_2}(T_F) / P_F) \cdot x_{H_2}^L$$

$$x_{CH_4}^V = pv_{CH_4} \cdot (P^o_{CH_4}(T_F) / P_F) \cdot x_{CH_4}^L$$

Membranes - static model

ON

$$F_{IN_H_2} = F_{OUT_H_2} + F_{RCHZ}$$

$$F_{IN_H_2} \cdot x_{H_2}^{IN_H_2} = F_{OUT_H_2} \cdot x_{H_2}^{OUT_H_2} + F_{RCHZ} \cdot x_{H_2}^{RCHZ}$$

$$x_{H_2}^{OUT_H_2} = f(x_{H_2}^{IN_H_2}, F_{RCHZ})$$

OFF

$$\frac{F_{RCHZ_H_2}}{F_{IN_H_2}} = 1$$

$$x_{H_2}^{RCHZ_H_2} = x_{H_2}^{IN_H_2}$$